Chapter 7

M icrowaves

7.1 introduction

Electromagnetic radiation travels at a constant speed in vacuum = 3×10^8 m/s.

| λ, m | Radiation |
|-------------------------|---------------------------|
| 1 | radio waves |
| 10^{-1} to 10^{-3} | microwave |
| 10^{-4} to 10^{-5} | infrared |
| 10 ⁻⁶ | visible light |
| 10^{-7} to 10^{-8} | ultraviolet |
| 10^{-9} to 10^{-13} | x-ray and gamma radiation |
| 10-14 | cosmic rays |

Microwaves (unlike light) can penetrate matter (almost all non- metallic materials) and are reflected (scattered) from internal boundaries.

- no mechanical contact, unlike ultrasonics.
- speed is 5 orders of magnitude larger than ultrasonics.
 - cannot detect time of arrival as in ultrasonics.
 - need to employ continuous wave or frequency modulated signal (no pulse mode).
 - rapid inspection is possible.
- skin depth in metal is a few mm, totally reflected on surface of metal.
- can readily penetrate many non-metals, plastics, ceramics, etc.

• physical phenomena: based on electromagnetic theory (not covered here in detail)

Source: microwave generator.

Modification: interaction with atoms and molecules (attenuation and thermal effects).

Detector: microwave receiver (antenna, transducer).

Indication: (continuous) wave amplitude, phase shift, frequency of transmitted or reflected signal.

Interpretation: will discuss through examples.

7.1.1 Thickness of Metal Plates

- Metal completely reflects microwaves.
- Both sides of metal plate must be illuminated.
- Amplitude dependence is not generally very strong, except if the plate is near the near field of the antenna (interference of waves). Then, the amplitude becomes a function of the distance between plate and source.
- See schematic of system based on amplitude $(d_1 + d_2 + t = constant)$.
- Can detect up to 25 μ m.
- Metal composition or surface condition does not affect the results.

7.2 Phase Measurements

- See schematic of Interferometer system.
- Output:

$$V_{out} = K \sin \frac{\phi_A - \phi_C}{4} \sin \frac{1}{2} \left[\frac{\phi_A + \phi_C}{2} - \phi_B \right]$$
(7.1)

• Phase Shifter introduces a phase shift of 90°; so that if ϕ_A leads ϕ_B by 90° and ϕ_C lags ϕ_B by 90°, the output of differential amplifier is zero.

- If thickness changes $(\phi_A \phi_B + \phi_C \phi_B)/2$ will no longer be zero.
- The output voltage \propto distance.
- Note: there is sensitivity to both amplitude and phase shift. There are also more advanced systems.

7.3 Surface Cracks in Metals

Monitor refection from surface.

- Since skin depth is very small, a few μ m, a crack must break through the surface of the metal.
- As crack opening increases, energy storage within the crack begins to dominate the crack response as frequency increases (very sensitive to crack opening).
- If frequency is very high, wave can propagate within crack and the crack response becomes very sensitive to crack depth.

7.4 Dielectric Plates

Non Metals: Thickness, composition, flaws.

Attenuation

- 1. interaction with free electrons (composition).
- 2. interaction with molecular dipoles (composition).
- 3. scattering from material discontinuity (flaws).
- 4. beam spreading.

7.4.1 Reflection

See diagram. Critical Angle: wave is completely trapped inside; see diagram.

- Standing wave is a wave trapped inside.
- There is always a standing wave, except for the Brewstel angle, if microwave is emitted from high ϵ to low ϵ .

• Position of defect if within the min or max of a standing wave (which depend on frequency) will cause reflection which is related to frequency



disturbance.

$$\rho = \frac{2jR\sin\phi}{\exp(j\phi) - R^2\exp(-j\phi)}$$
(7.2)

$$r = \frac{1 - R^2}{\exp(j\phi) - R^2 \exp(-j\phi)}$$
(7.3)

where ρ and τ are respectively, the reflection and attenuation coefficients.

$$R = \text{Reflection Ratio} = (Z - 1)/(Z + 1)$$
(7.4)
$$Z = \text{intrinsic impedance of plate}$$

$$Z = \frac{\sqrt{\epsilon/\epsilon_0 - \sin^2 \theta_i}}{(\epsilon/\epsilon_0) \cos \theta_i} \quad \text{for // polarization}$$
(7.5)

$$Z = \frac{\cos \theta_i}{\sqrt{\epsilon/\epsilon_0 - \sin^2 \theta_i}} \quad \text{for } \perp \text{ polarization}$$
(7.6)

 ϕ = electrical thickness of plate

$$\phi = k d \sqrt{(\epsilon/\epsilon_0 - \sin^2 \theta_i)}$$
(7.7)

where $k = 2\pi/\lambda$. See graph for ρ and τ vs. ϕ :

- ρ is more sensitive to changes in ϕ than τ .
- At $\phi = \pi/2$ or multiples of $\pi/2$, the slope is zero (poor sensitivity).
- Amplitude is most sensitive to changes in electrical thickness when ϕ is multiples of π (largest slope).

7.5. FLAWS

7.5 Flaws

7.5.1 Voids

- Discontinuity of scattered radiation (reduced intensity).
- Amount of scattering increases with ϵ and frequency.
- Size of flaw $\approx \lambda$; small void requires high frequency.

7.5.2 Delamination

- This is essentially a packed-shaped void filled with air (delamination between two adhesively bonded dielectric materials).
- R < 0.3, $\rho = 2j \exp(-j\phi)R\sin\phi$.
- If thickness $<< \lambda$, i.e. $\phi << 1$, $\rho \propto \phi$.

7.5.3 Porosity

Large number of small voids distributed in some regions of materials; ϵ causes change in ϕ ; same techniques as in delamination.

7.5.4 Inclusions

Energy scattered by inclusions.

- $\lambda >>$ radius of inclusion, a (assumed to be a sphere).
- Above is called Rayleigh region: $\frac{2\pi a}{\lambda} < 0.4$.
- In far field: Prob. of scattering = scattering cross section, σ :

$$\sigma(\text{backscattering}) = \lambda^2 \frac{9}{\pi} \left(\frac{2\pi a}{\lambda}\right)^6 \tag{7.8}$$

$$\sigma(\text{forward scattering}) = \lambda^2 \frac{1}{4\pi} \left(\frac{2\pi a}{\lambda}\right)^6 \tag{7.9}$$

• Backscattering is stronger than forward scattering.

7.5.5 Material Properties

Change in ϵ : moisture content: water has a very high ϵ , very strong absorber of microwave.

7.6 Graphs

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Figure 7.1: Amplitude Method for Thickness Measurement

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Figure 7.2: Phase-Shift Method for Thickness Measurement

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Figure 7.5: Electrical Thickness vs. Reflection and Transmission coefficients



Figure 7.6: Phase-Shift vs. Electrical Thickness

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